

§ symplectic forms

A symplectic form ω on a vector space V

$$\omega: V \times V \rightarrow R$$

1. Skew-symmetric

2. Non-degenerate if $\omega(v, w) = 0$ for $\forall w \in V$ then $v=0$

And (V, ω) is called a symplectic space

There exists a basis $e_1, e_2, \dots, e_n, f_1, \dots, f_n$ such that

$$\omega(e_i, e_i) = \omega(f_j, f_j) = 0 \text{ and } \omega(e_i, f_j) = \delta_{ij}$$

Definition

Let (V, ω) be a symplectic space, then for any subspace W of V

1. W is isotropic if $\omega(w_1, w_2) = 0$ for $\forall w_1, w_2 \in W$

Denote W^ω by $W^\omega := \{v \in V : \omega(w, v) = 0, \forall w \in W\}$, it is easy to see that W is isotropic $\Leftrightarrow W \subseteq W^\omega$

2. W is Lagrangian if W is an isotropic space of maximal dimension

Definition

Let $(V, \omega), (V', \omega')$ be symplectic vector space.

$\phi: V \rightarrow V'$ such that $\omega'(\phi(u), \phi(v)) = \omega(u, v), \forall u, v \in V$ is a linear isomorphism

In other words $\phi^*\omega' = \omega$

Then we say $(V, \omega), (V', \omega')$ are symplectomorphic

Definition

A symplectic form on a manifold is a differential 2-form ω on M such that

1. $\omega_p: T_p M \times T_p M \rightarrow R$ is symplectic $\forall p \in M$

在流形上取局部座標系 $\omega = \frac{1}{2} \omega_{ij} dx^i \wedge dx^j$

non-degenerate $\det(\omega_{ij}) \neq 0$

2. ω is closed

Then (M, ω) is a symplectic manifold

稱 ω 為 M 上的辛結構。

例 10.1

相位空間(configuration space) N 的餘切叢 $M = T^*N$ 對於物理應用而言是最重要的。

在 T^*N 座標系 $\{p_i, q^j\}$ 引入一 regular 1-form $\vartheta = \sum_i p_i dq^i \in \Lambda^1(M)$

則 $\omega = d\vartheta = \sum_i dp_i \wedge dq^i \in \Lambda^2(M)$ 紿出 M 上的辛結構。

ϑ 稱為 symplectic potential。

在經典力學中 N 稱為相位空間， M 稱為哈密頓體系的相空間。

$\{p_i\}$ 為廣義座標， $\{q^i\}$ 為對偶的廣義動量。

例 10.2 李群的餘伴隨軌道 p.310 侯

例 10.3 複投射流形 Kahler 流形

例 A particle (x_1, x_2, x_3) moving in R^3 with momentum $M = T^*N$ m (p_1, p_2, p_3) 。

Suppose the energy function $H(x, p) = \frac{1}{2m}|p|^2 + U(x)$, where $U(x)$ is the potential

energy function satisfying $m \frac{d^2 x}{dt^2} = -\nabla U(x)$

Then we have the following Hamilton equations

$$\begin{cases} \frac{dx_i}{dt} = \frac{\partial H}{\partial p_i} \\ \frac{dp_i}{dt} = -\frac{\partial H}{\partial x_i} \end{cases}$$

In classical mechanics, solving Hamilton equations is equivalent to solving the Euler-Lagrange equation of the Lagrange L。

Let our symplectic manifold be R^6 with coordinates $(x_1, x_2, x_3, p_1, p_2, p_3)$

Then $\omega = \sum_i dx_i \wedge dp_i$

$$\alpha \in T^*M, \pi(x^i, p_i) = (x^i)$$

$$v = \sum_i dx^i(v) \frac{\partial}{\partial x^i} + \sum_i dp_i \frac{\partial}{\partial p_i} \in T_\alpha(T^*M)$$

$\theta \in \Omega^1(T^*M)$ is a 1-form given by $\theta_\alpha(v) := \alpha((d\pi)_\alpha(v))$

$$\text{Then } (d\pi)_\alpha(v) = \sum_i dx^i(v) \frac{\partial}{\partial x^i}$$

$$\theta_\alpha(v) = \alpha((d\pi)_\alpha(v)) = \sum_i p_i dx^i(\sum_j dx^j(v) \frac{\partial}{\partial x^j}) = \sum_i p_i dx^i(v)$$

$$\theta = \sum_i p_i dx^i \text{ is a regular 1-form}$$

$\omega = d\theta = \sum_i dp_i \wedge dx^i$ is a 2-form called canonical symplectic form on T^*M

(註:若取 local coordinates 為 $\{p_i, q^i\}_{i=1}^n$ 則 $\theta = \sum_i p_i dq^i, \omega = d\theta = \sum_i dp_i \wedge dq^i$)

Proposition

The canonical symplectic form ω is closed and nondegenerate.

Moreover $\omega^n = \omega \wedge \dots \wedge \omega$ is a volume form.

由於 ω 為非退化，故可在切場與餘切場之間建立一對映關係

$$\mu: \chi(M) \rightarrow \Lambda^1(M)$$

$$X = \xi^i \frac{\partial}{\partial x^i} \rightarrow -i_X \omega = -\omega_{ij} \xi^i dx^j$$

$$\text{i.e. } \mu(X) = -i_X \omega = -\omega_{ij} \xi^i dx^j$$

Proposition

The Hamilton equations are the equations for the flow of the vector field X_H satisfying $i(X_H)\omega = -dH$

Proof

The Hamilton equations yield the flow of the vector field

$$X_H = \sum_i \left(\frac{\partial H}{\partial p_i} \frac{\partial}{\partial x^i} - \frac{\partial H}{\partial x^i} \frac{\partial}{\partial p_i} \right), \quad \omega = d\theta = \sum_i dp_i \wedge dx^i$$

Therefore

$$i(X_H)\omega = i(X_H) \sum_i (dp_i \otimes dx^i - dx^i \otimes dp_i)$$

$$= \sum_i \left(-\frac{\partial H}{\partial x^i} dx^i - \frac{\partial H}{\partial p_i} dp_i \right) = -dH$$

Definition

The Hamiltonian flow generated by $F \in C^\infty(T^*M)$ is the flow of the unique vector field $X_F \in \chi(T^*M)$ such that $i(X_F)\omega = -dF$

Proposition

Hamiltonian flows preserve their generating functions. i.e. $X_F F = 0$

Proof

$X_F F = dF(X_F) = (-i(X_F)\omega)(X_F) = -\omega(X_F, X_F) = 0$ as ω is alternating.

Proposition

Hamiltonian flows preserve the canonical symplectic form.

If $\varphi_t : T^*M \rightarrow T^*M$ is a Hamiltonian flow then $\varphi^*\omega = \omega$

換句話說 在辛流形 (M, ω) 上 保辛結構變換的無窮小生成元 $X \in \chi(M)$ 稱為辛向量場，滿足 $L_X \omega = 0$ ($di_X \omega = 0$ i.e. $i_X \omega$ is closed.)

假設 $-i_X \omega = df$ ，

注意到辛結構 ω 为非退化 2 形式，(10.4)式映射 μ 为 1-1 对应的实线性映射，存在逆映射 μ^{-1} ，对于流形上任意光滑函数 $f \in F(M)$ ，映射

$$\mu^{-1} : df \in \Lambda^1(M) \rightarrow X_f \in \chi(M) \quad (10.9)$$

向量场 $X_f = \mu^{-1}(df)$ 称为哈密顿矢场，满足

$$-i_{X_f} \omega = df \quad (10.9a)$$

我们知道正合形式必是闭形式，反之不一定。对应地，哈密顿矢场必是辛矢场，反之不一定。用 $\text{Ham}(M)$ 表示辛流形上所有哈密顿矢场集合，以上分析表明

$$\text{Ham}(M) \subset \text{Sym}(M) \subset \chi(M)$$

哈密頓向量場一定是辛向量場，反之 不一定成立。

Liouville theorem

Hamiltonian flows preserve the integral with respect to the symplectic volume form.

$\varphi_t : T^*M \rightarrow T^*M$ is a Hamiltonian flow and $F \in C^\infty(T^*M)$ is a compactly

supported function then $\int_{T^*M} F \circ \varphi_t = \int_{T^*M} F$

Proof

$$\varphi_t^* \omega = \omega$$

$$\varphi_t^*(\omega^n) = (\varphi_t^*\omega)^n = \omega^n$$

$$\begin{aligned} \int_{T^*M} F \circ \varphi_t &= \int_{T^*M} (F \circ \varphi_t) \omega^n = \int_{T^*M} (F \circ \varphi_t) \varphi_t^*(\omega^n) \\ &= \int_{T^*M} \varphi_t^*(F \omega^n) = \int_{T^*M} F \omega^n = \int_{T^*M} F \end{aligned}$$

Poincare recurrence theorem