

EXERCISE 6.1

To the four-vector $\mathbf{X} = (x^0, x^1, x^2, x^3)$ of Minkowski space we make correspond the matrix $\chi = x^i \sigma_i$, where σ_i denotes the Pauli matrices.

1. Write the matrix χ explicitly and calculate the inverse correspondence.
2. Calculate the scalar product $(\mathbf{X}, \mathbf{X})$ as a function of χ .
3. Let A be a matrix belonging to the group $\mathbf{SL}(2, \mathbb{C})$. Determine a transformation which preserves the scalar product of four-vectors.
4. From this deduce that there exists a Lorentz transformation Λ_A corresponding to the matrix A .
5. Show that there exists a homomorphism between the groups $\mathbf{SL}(2, \mathbb{C})$ and $\mathbf{SO}(3, 1)^\dagger$.

EXERCISE 6.2

The infinitesimal matrices Y_{ij} of the group $\mathbf{SO}(3, 1)^\dagger$ are given by (6.1.9).

1. Calculate the commutators $[Y_{02}, Y_{01}]$, $[Y_{12}, Y_{01}]$, $[Y_{02}, Y_{12}]$.
2. Compare them with the commutation relations of $\mathbf{SO}(3)$.

EXERCISE 6.3

Consider two spinors (ψ^1, ψ^2) and (ϕ^1, ϕ^2) of four-dimensional space.

1. Show that the product $(\psi^1 \phi^2 - \psi^2 \phi^1)$ is invariant under all transformations of the group $\mathbf{SL}(2, \mathbb{C})$.
2. In order that the product $(\psi^1 \phi^2 - \psi^2 \phi^1)$ may be written in the classical form $\psi^k \phi_k$ of a scalar product, determine the expression for the 'covariant' components ϕ_k as well as the components of the fundamental tensor.

EXERCISE 6.4

Consider two Cartesian frames of reference $Oxyz(t)$ and $O'x'y'z'(t')$ which are moving with respect to each other at a speed v along the axis Ox parallel to $O'x'$.

1. Recall the formulas for the Lorentz transformation between two reference frames. Set

$$\beta = \frac{v}{c}.$$

2. For the moment use the following notations

$$\begin{array}{cccc} ct = x^0, & x = x^1, & y = x^2, & z = x^3, \\ ct' = x^{0'}, & x' = x^{1'}, & y' = x^{2'}, & z' = x^{3'}. \end{array} \quad (6.4.26)$$

Set

$$\gamma = (1 - \beta^2)^{-1/2}.$$

Calculate the matrix of the Lorentz transformation between the two reference frames.

3. Show that we can, indeed, set

$$\gamma = \cosh \varphi, \quad \gamma\beta = \sinh \varphi.$$