

Let  $(M, g)$  be a Riemannian manifold.

- (a) Write down the definition of Levi-Civita connection  $\nabla$
- (b) Let  $\{e_i\}$  be a local frame of the tangent bundle induced by a coordinate chart. Write down the definition of Christoffel symbols  $\Gamma_{ij}^k$  and prove that  $\nabla_{e_i} e_j = \Gamma_{ij}^k e_k$ .

(a) The Levi-Civita connection on a Riemannian manifold  $(M, g)$  is the unique affine connection that is torsion-free and metric compatible.

1. Torsion-free :  $\nabla_X Y - \nabla_Y X = [X, Y]$  for all vector fields  $X, Y$
2. Metric compatible :  $\nabla g = 0$  or equivalently,  $X(g(Y, Z)) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z)$  for all  $X, Y, Z$ .

(b) Christoffel symbols 的歷史背景

1. 研究曲線坐標中的微分運算
2. 引入聯絡係數
3. 與高斯的曲面理論關聯
4. 與 Levi-Civita 的關係

之後，Tullio Levi-Civita 在 1917 年進一步發展了這一概念，並確立了 Levi-Civita 聯絡，即基於度量張量導出的唯一無挫曲(torsion-free)且與度量相容的聯絡。這使得 Christoffel 符號在廣義相對論中成為關鍵工具，負責描述時空的彎曲性與自由落體運動。

$$\text{證明 } \Gamma_{ij}^k = \frac{1}{2} g^{lk} \left( \frac{\partial g_{jl}}{\partial x^i} + \frac{\partial g_{il}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^l} \right)$$

1. 考慮度量張量在座標基底下的協變導數為零，即

$$\nabla_k g_{ij} = \frac{\partial g_{ij}}{\partial x^k} - \Gamma_{ik}^l g_{lj} - \Gamma_{jk}^l g_{il} = 0 \quad (\text{即 } \nabla g = 0, \nabla \text{ is metric compatible, 或者})$$

寫成  $\nabla_\lambda g_{\mu\nu} = 0$  )

將上式對索引重新排列，得到三個方程式：

1.  $\frac{\partial g_{ij}}{\partial x^k} = \Gamma_{ik}^l g_{lj} + \Gamma_{jk}^l g_{il}$
2.  $\frac{\partial g_{jk}}{\partial x^i} = \Gamma_{ji}^l g_{lk} + \Gamma_{ki}^l g_{jl}$
2.  $\frac{\partial g_{ki}}{\partial x^j} = \Gamma_{kj}^l g_{li} + \Gamma_{ij}^l g_{kl}$
3. 將此三方程相加。再取  $g^{kl}$  即可。這個推導顯示：Christoffel 符號是唯一滿足度量相容性與無挫曲條件的聯絡係數。
4. Christoffel 符號的存在確保測地線方程。

$$X = \sum_i X^i \frac{\partial}{\partial x^i}, Y = \sum_i Y^i \frac{\partial}{\partial x^i} \quad \text{then} \quad \nabla_X Y = \sum_i (XY^i + \sum_{j,k} \Gamma_{jk}^i X^j Y^k) \frac{\partial}{\partial x^i}$$

Let  $\{e_i\}$  be the local frame induced by a coordinate chart  $(U, x^i)$ , so  $e_i = \frac{\partial}{\partial x^i}$ . The covariant derivative  $\nabla_{e_i} e_j$  is defined by its action on the coordinate basis:

$$\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \Gamma_{ij}^k \frac{\partial}{\partial x^k},$$

where  $\Gamma_{ij}^k$  are the Christoffel symbols of the connection. Substituting  $e_i = \frac{\partial}{\partial x^i}$  and  $e_k = \frac{\partial}{\partial x^k}$ , this becomes:

$$\nabla_{e_i} e_j = \Gamma_{ij}^k e_k.$$