

Consider the smooth Riemannian 2-manifold  $D = \{(x, y) \in \mathbb{R}^2; x^2 + y^2 < 1\}$  with a metric

$$\frac{dx^2 + dy^2}{g^2(x, y)} \circ \text{Here } g(x, y) = \frac{1}{2}[1 - (x^2 + y^2)]$$

(1) Find the frame field  $\{E_1, E_2\}$  and dual coframe field  $\{\theta_1, \theta_2\}$

(2) Show that the connection 1-form  $\omega_{12} = g_y \theta_1 - g_x \theta_2$

(3) Show that the Gaussian curvature  $K = -1$

(4) Let  $\Delta$  be a geodesic triangle in  $D$  . Show that  $area(\Delta) = \pi - (i_1 + i_2 + i_3)$  , here

$i_1, i_2, i_3$  are the interior angles at the vertices of  $\Delta$

$$ds^2 = \frac{dx^2 + dy^2}{g^2(x, y)} = \theta_1^2 + \theta_2^2 \quad , \quad \text{where } \theta_1 = \frac{dx}{g(x, y)}, \theta_2 = \frac{dy}{g(x, y)}$$

$$E_1 = g(x, y) \frac{\partial}{\partial x}, E_2 = g(x, y) \frac{\partial}{\partial y} \quad \text{with } \theta_i(E_j) = \delta_{ij}$$

For a 2D Riemannian manifold , the first Cartan structure equation is :

$$d\theta_i + \sum_j \omega_{ij} \wedge \theta_j = 0$$

Where  $\omega_{ij}$  are the connection 1-forms . In 2D , there is only one independent

connection 1-form  $\omega_2$  because  $\omega_{12} = -\omega_{21}$

$$d\theta_1 = d\left(\frac{dx}{g}\right) = \frac{-dg}{g^2} = -\frac{g_x dx + g_y dy}{g^2} \wedge dx = \frac{g_y}{g^2} dx \wedge dy$$

$$d\theta_2 = d\left(\frac{dy}{g}\right) = -\frac{g_x dx + g_y dy}{g^2} \wedge dy = -\frac{g_x}{g^2} dx \wedge dy$$

Apply Cartan first structure equation

$$d\theta_1 + \omega_2 \wedge \theta_2 = 0 \quad \frac{g_y}{g^2} dx \wedge dy + \omega_2 \wedge \frac{dy}{g} = 0$$

$$\omega_2 = g_y \frac{dx}{g} + (\text{terms involving } dy)$$

$$d\theta_2 - \omega_2 \wedge \theta_1 = 0 \quad \frac{g_x}{g^2} dx \wedge dy - \omega_2 \wedge \frac{dx}{g} = 0 \quad \text{this gives } \omega_2 \wedge dx = \frac{g_x}{g} dx \wedge dy$$

Thus  $\omega_2 = -g_x \frac{dy}{g} + (\text{terms involving } dx)$

Finally , we get  $\omega_2 = g_y \theta_1 - g_x \theta_2$

Second Cartan structure equation  $\Omega_2 = d\omega_2 = K\theta_1 \wedge \theta_2$

$$d\omega_2 = d(g_y\theta_1) - d(g_x\theta_2) = (g_{yy}dy + g_{yx}dx) \wedge \theta_1 + g_y d\theta_1 - (g_{xx}dx + g_{xy}dy) \wedge \theta_2 - g_x d\theta_2$$

Given that  $g(x, y) = \frac{1}{2}[1 - (x^2 + y^2)]$ , then

$$g_x = -x, g_y = -y, g_{xx} = -1, g_{yy} = -1, g_{xy} = g_{yx} = 0$$

$$d\omega_2 = -dy \wedge \theta_1 + dx \wedge \theta_2 + \frac{x^2 + y^2}{g^2} dx \wedge dy$$

$$-dy \wedge \theta_1 + dx \wedge \theta_2 = \frac{2}{g} dx \wedge dy = \frac{2g}{g^2} dx \wedge dy$$

$$d\omega_2 = \frac{[1 - (x^2 + y^2)] + (x^2 + y^2)}{g^2} dx \wedge dy = \frac{dx \wedge dy}{g^2}$$

Since  $\theta_1 \wedge \theta_2 = \frac{dx \wedge dy}{g^2(x, y)}$ , we rewrite :  $d\omega_2 = -\frac{dx \wedge dy}{g^2}$  (?)

$$d\omega_2 = K\theta_1 \wedge \theta_2 \text{ thus } K = -1$$

這是一個 hyperbolic plane

Poincare disk model

In two dimensions, with respect to these frames and the [Levi-Civita connection](#), the connection forms are given by the unique skew-symmetric matrix of 1-forms  $\omega$  that is [torsion-free](#), i.e., that satisfies the matrix equation  $0 = d\theta + \omega \wedge \theta$ . Solving this equation for  $\omega$  yields

$$\omega = \frac{2(y dx - x dy)}{1 - |\mathbf{x}|^2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix},$$

where the curvature matrix is

$$\Omega = d\omega + \omega \wedge \omega = d\omega + 0 = \frac{-4 dx \wedge dy}{(1 - |\mathbf{x}|^2)^2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

Therefore, the curvature of the hyperbolic disk is

$$K = \Omega_2^1(e_1, e_2) = -1.$$