

Immersion vs Embedding

An **immersion** is a smooth map between manifolds where the derivative (or differential) is injective (one-to-one) at every point ◦

This means the map preserves the local structure of the manifold without any "folding" or "overlapping" at the infinitesimal level ◦ However, globally, an immersion may still have self-intersections or other complexities ◦

Key Properties of Immersion:

1. Locally injective (no folding at the infinitesimal level) ◦
2. May have self-intersections or overlaps globally ◦
3. Does not necessarily preserve the global topology ◦

Example of Immersion:

- The **Klein bottle** can be immersed in 3D space, but it cannot be embedded in 3D space without self-intersections ◦ In 3D, the Klein bottle appears to intersect itself, but at every point, the map is still smooth and locally injective ◦

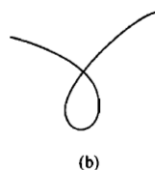
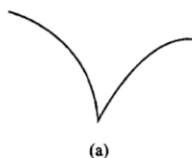
An **embedding** is a stronger condition than an immersion ◦ It is a smooth map between manifolds that is both an immersion and injective (one-to-one) globally ◦ This means the map preserves both the local and global structure of the manifold, with no self-intersections or overlaps ◦

Key Properties of Embedding:

1. Locally injective (like an immersion) ◦
2. Globally injective (no self-intersections or overlaps) ◦
3. Preserves the global topology of the manifold ◦

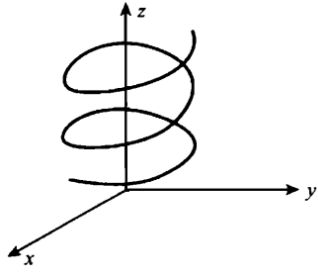
Example of Embedding:

- A **circle** can be embedded in 2D or 3D space without self-intersections ◦ For instance, the unit circle defined by $x^2 + y^2 = 1$ in 2D is an embedding because it has no overlaps or intersections ◦



(a) is not an immersion

(b) Is an immersion, but not an embedding



$\varphi: \mathbb{R} \rightarrow \mathbb{R}^3, \varphi(t) = (\cos t, \sin t, t)$ is an embedding