

高斯絕妙定理是高斯在 1827 年證明的。

此定理說高斯曲率是曲面的內秉(intrinsic)性質，由第一基本式決定。

第一基本式 $ds^2 = Edu^2 + 2Fdudv + Gdv^2$

在曲面 M 上，若有局部坐標系 (u, v) 其所有 u 曲線都是 M 上的么速測地線，且 u 曲線與 v 曲線在相交的地方都互相垂直，則稱 (u, v) 是 M 上的一個(局部)測地坐標系。

即 $ds^2 = du^2 + Gdv^2$ 初等微分幾何講稿 p.116 這裡有測地坐標系的製作；
大域微分幾何(上) p.15

§ 定理(Gauss Theorema Egregium)

Gauss 曲率 $K = -\frac{g_{uu}}{g}$

(或者寫成 $K = -\frac{1}{\sqrt{G}} \frac{\partial^2 \sqrt{G}}{\partial u^2}$ ，其中 $g = \sqrt{G}$)

證明

建立測地坐標系， $g^2 = G$

$\frac{\partial}{\partial u} X_{uv} = \frac{\partial}{\partial v} X_{uu}$ ，兩邊對 X_v 做內積，故事從這裡說起。

$\langle \frac{\partial}{\partial u} X_{uv}, X_v \rangle = \langle \frac{\partial}{\partial v} X_{uu}, X_v \rangle \dots (*)$

$\therefore \frac{\partial}{\partial u} \langle X_{uv}, X_v \rangle = \langle \frac{\partial}{\partial u} X_{uv}, X_v \rangle + \langle X_{uv}, X_{uv} \rangle$

$\therefore (*)$ 的左式 $\langle \frac{\partial}{\partial u} X_{uv}, X_v \rangle = \frac{\partial}{\partial u} \langle X_{uv}, X_v \rangle - \langle X_{uv}, X_{uv} \rangle$

同理，右式 $\langle \frac{\partial}{\partial v} X_{uu}, X_v \rangle = \frac{\partial}{\partial v} \langle X_{uu}, X_v \rangle - \langle X_{uu}, X_{vv} \rangle$

$g^2 = X_v \cdot X_v$ ， $\frac{\partial}{\partial u} g^2 = 2X_{uv} \cdot X_v$ ， $\therefore X_{uv} \cdot X_v = \frac{1}{2} \frac{\partial}{\partial u} g^2 = gg_u$

$\frac{\partial}{\partial u} \langle X_{uv}, X_v \rangle = \frac{\partial}{\partial u} gg_u = g_u^2 + gg_{uu}$

此時建立的 orthonormal frame 是 $X_1 = X_u, X_2 = \frac{X_v}{g}, X_3 = N = X_1 \times X_2$

X_{uv} 表成 X_u, X_v, N 的線性組合

$X_{uv} = \langle X_{uv}, X_u \rangle X_u + \langle X_{uv}, X_v \rangle \frac{X_v}{g} + \langle X_{uv}, N \rangle N$

$\therefore X_u \cdot X_u = 1, \therefore X_{uv} \cdot X_u = 0$

$$X_{uv} \cdot X_{uv} = \langle X_{uv}, X_v \rangle^2 \frac{X_v \cdot X_v}{g^4} + \langle X_{uv}, N \rangle^2 = \langle X_{uv}, X_v \rangle^2 \frac{1}{g^2} + \langle X_{uv}, N \rangle^2$$

$$= (gg_u)^2 \times \frac{1}{g^2} + \langle X_{uv}, N \rangle^2 = g_u^2 + f^2$$

$\therefore X_{uu}$ 只有法部, $\therefore X_{uu} = \langle X_{uu}, N \rangle N$

$$\langle X_{uu}, X_{vv} \rangle = \langle \langle X_{uu}, N \rangle N, X_{vv} \rangle = \langle X_{uu}, N \rangle \langle X_{vv}, N \rangle = \bar{e} \bar{g}$$

$$\text{(此處 } \bar{g} = X_{vv} \cdot N, K = \frac{\bar{e} \bar{g} - f^2}{EG - F^2} \text{。)}$$

$$\text{所以(*)的左式} = g_u^2 + gg_{uu} - g_u^2 - f^2 = gg_{uu} - f^2$$

$$\text{右式} = \frac{\partial}{\partial v} \langle X_{uu}, X_v \rangle - \langle X_{uu}, X_{vv} \rangle, X_{uu} = \langle X_{uu}, N \rangle N$$

$$= -\langle \langle X_{uu}, N \rangle N, X_{vv} \rangle = -\langle X_{uu}, N \rangle \langle X_{vv}, N \rangle = -\bar{e} \bar{g}$$

$$gg_{uu} - f^2 = -\bar{e} \bar{g}, g^2 = G$$

$$g_{uu} = -\frac{\bar{e} \bar{g} - f^2}{\sqrt{G}}, \text{ 所以 } K = \frac{\bar{e} \bar{g} - f^2}{EG - F^2} = \frac{\bar{e} \bar{g} - f^2}{G} = -\frac{g_{uu}}{g}$$

以上即 semigeodesic coordinates $g_{11} = 1, g_{12} = 0, g_{22} = G$ p.183

$$\text{此時 } \Gamma_{11}^1 = \Gamma_{11}^2 = \Gamma_{12}^1 = 0, \Gamma_{12}^2 = \frac{1}{2G} \frac{\partial G}{\partial u}, \Gamma_{22}^1 = -\frac{1}{2} \frac{\partial G}{\partial u}, \Gamma_{22}^2 = \frac{1}{2G} \frac{\partial G}{\partial v}$$

$$\text{Where } \Gamma_{ij}^k = \frac{1}{2} g^{kl} \left(\frac{\partial g_{jl}}{\partial u^i} + \frac{\partial g_{il}}{\partial u^j} - \frac{\partial g_{ij}}{\partial u^l} \right)$$

Abraham Goetz 的書是用 Christoffel symbol 處理。 p.186

§ Introduction to Differential Geometry Abraham Goetz p.188

For isothermic coordinates, $g_{11} = g_{22} = \rho^2, g_{12} = 0$

$$\Gamma_{11}^1 = \Gamma_{12}^2 = -\Gamma_{22}^1 = \frac{\partial \ln \rho}{\partial u}$$

$$\Gamma_{12}^1 = -\Gamma_{22}^1 = -\Gamma_{11}^2 = \frac{\partial \ln \rho}{\partial v}$$

$$K = -\frac{1}{\rho^2} \Delta \rho, \text{ where } \Delta f = \frac{\partial^2 f}{\partial u^2} + \frac{\partial^2 f}{\partial v^2} \text{ is the Laplace operator}$$

§ 建立一個測地坐標系，稍懂。

那麼，如何用 exponential map 建構一個 Riemann normal coordinates(簡正座標) at p 。

Now we see for any $p \in M$, there exists a neighborhood $U \subset M$ of p and a neighborhood $V \subset T_p M$ of 0 so that the exponential map

$$\exp_p : V \rightarrow U$$

is a diffeomorphism. But $T_p M$, and thus V , is Euclidian, so the triple $\{\exp_p^{-1}, U, V\}$ form a local chart of M near p . Usually one takes such U 's to be geodesic balls (and thus V to be Euclidean balls). We will fix an orthonormal basis $\{e_i\}$ of $T_p M$, which gives us linear coordinates for V . We denote the corresponding coordinate functions on U by $\{x^i\}$.

Definition 1.1. The local chart $\{U; x^1, \dots, x^m\}$ described above is called *normal coordinate system* at p .

Lemma

Let $\{U; x^1, x^2, \dots, x^m\}$ be a normal coordinate system at p . Then for all $1 \leq i, j, k \leq m$

$$(1) g_{ij}(p) = \delta_{ij} \quad (2) \Gamma_{ij}^k = 0 \quad (3) \partial_k g_{ij}(p) = 0$$