



高斯 Carl Friedrich Gauss 1777-1855

$$\iint_M K dA + \int_{\partial M} \kappa_g ds = 2\pi\chi(M)$$

高斯-博內定理與曲面的拓撲性質有關，
它的特例(在平面上)稱為切線轉角定理。

陳省身先生在 1944 年把它推廣了，在物理上有好幾個應用。M is a closed oriented Riemannian manifold with an

even dimension d , then $\int_M \Omega = \chi(M)$ where $\Omega_i^j = R_{ikj}^j d\omega^k \wedge d\omega^l$

[Oliver Knill](#) 先生[圖論的 Gauss-Nonnet-Chern 定理]

<https://www.youtube.com/watch?v=-UNkiKDidI8>

Something interesting !

§01 敘述

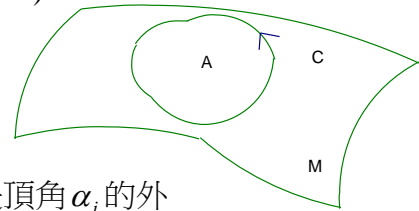
1. C 是曲面 M 上的 Jordan curve(平滑、封閉、簡單。)

$$\text{則 } \iint_A K dA + \int_C \kappa_g ds = \int_C d\theta = 2\pi$$

2. 若 C 是分段平滑的, A compact, oriented, 則

$$\iint_A K dA + \int_C \kappa_g ds + \sum_i (\pi - \alpha_i) = 2\pi\aleph, \text{ 其中 } \pi - \alpha_i \text{ 是頂角 } \alpha_i \text{ 的外}$$

角, \aleph 是 Euler 示性數。



§02 預備定理

1. 何謂(1)測地曲率 geodesic curvature (2)高斯曲率

$$\frac{dT}{ds} = \kappa_n N + \kappa_g U, U = N \times T$$

則 $\kappa_g = \frac{dT}{ds} \cdot U$ 是為測地曲率

半徑為 r 的球面 $K = \frac{1}{r^2}$

2. Green 定理

C 是 piecewise smooth Jordan curve

$$\text{則 } \iint_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \oint_C P dx + Q dy$$

例 $C: x^2 + \frac{y^1}{4} = 1$, 力場 $F(x, y) = [3x + y, -x + 2y]$ 加諸質點 P , 沿 C 逆時針繞一圈所作

$$\text{的功 } W = \oint_C F \cdot dx = \oint_C P dx + Q dy = \dots = -4\pi$$

3. 取 lines of curvature 作參數曲線時

$$K = \frac{e g - f^2}{E G - F^2} = \frac{1}{-\sqrt{E G}} \left\{ \frac{\partial}{\partial u} \left(\frac{1}{\sqrt{E}} \frac{\partial \sqrt{G}}{\partial u} \right) + \frac{\partial}{\partial v} \left(\frac{1}{\sqrt{G}} \frac{\partial \sqrt{E}}{\partial v} \right) \right\}$$

4. Liouville's lemma

u-curve, v-curve 在曲面 M 上形成一正交網, $T_P(M)$ 由 T, U 所張。

假設 T 與 u-curve 夾角為 θ , 則 $\begin{cases} T = i_1 \cos \theta + i_2 \sin \theta \\ U = -i_1 \sin \theta + i_2 \cos \theta \end{cases}, T \cdot i_1 = \cos \theta$

$$ds_1 = ds \cos \theta, ds_2 = ds \sin \theta, ds^2 = ds_1^2 + ds_2^2$$

定義 $\kappa_g = \frac{dT}{ds} \cdot U$

則 $\kappa_g = \kappa_1 \cos \theta + \kappa_2 \sin \theta + \frac{d\theta}{ds}$, 其中 $\kappa_1 = (\kappa_g)_{u\text{-curve}} = \frac{di_1}{ds_1} \cdot i_2 = -i_1 \cdot \frac{di_2}{ds_1}$

$$\kappa_2 = (\kappa_g)_{v\text{-curve}} = \frac{-di_2}{ds_2} \cdot i_1 = i_2 \cdot \frac{di_1}{ds_2}$$

$$\frac{di_1}{ds} = \frac{di_1}{ds_1} \frac{ds_1}{ds} + \frac{di_1}{ds_2} \frac{ds_2}{ds} = \cos \theta \frac{di_1}{ds_1} + \sin \theta \frac{di_1}{ds_2}$$

$$\frac{di_2}{ds} = \dots = \cos \theta \frac{di_2}{ds_1} + \sin \theta \frac{di_2}{ds_2}$$

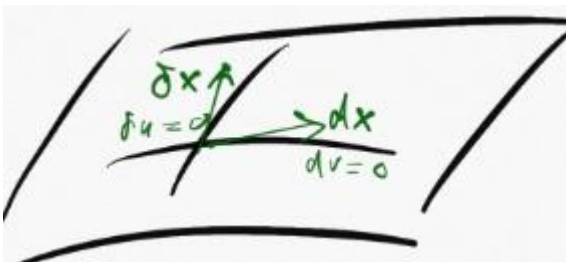
$$U = -i_1 \sin \theta + i_2 \cos \theta$$

$$\frac{di_1}{ds} \cdot U = \kappa_1 \cos^2 \theta + \kappa_2 \sin \theta \cos \theta, \frac{di_2}{ds} \cdot U = \kappa_1 \sin \theta \cos \theta + \kappa_2 \sin^2 \theta$$

$$\frac{dT}{ds} = \cos \theta \frac{di_1}{ds} + \sin \theta \frac{di_2}{ds} + U \frac{d\theta}{ds}$$

$$\frac{dT}{ds} \cdot U = \dots = \kappa_1 \cos \theta + \kappa_2 \sin \theta + \frac{d\theta}{ds}$$

§03 證明



選一正交坐標系 $F=0$

$$dA = |dx \times \delta x| = \sqrt{EG - F^2} du \delta v = \sqrt{EG} du \delta v$$

在 u-curve 上,

$$ds_1^2 = Edu^2 + 2Fdudv + Gdv^2 = Edu^2$$

在 v-curve 上,

$$ds_2^2 = \dots = Gdv^2, ds_2 = \sqrt{G} dv$$

所以 $ds_1 = \sqrt{E}du = ds \cos \theta, ds_2 = \sqrt{G}dv = ds \sin \theta$, 由 Liouville's lemma

$$\kappa_g ds = d\theta + \kappa_1 \cos \theta ds + \kappa_2 \sin \theta ds = d\theta + \kappa_1 \sqrt{E}du + \kappa_2 \sqrt{G}dv$$

在 u-curve 上, $\frac{dv}{ds} = 0, \frac{du}{ds} = \frac{1}{\sqrt{E}}, \kappa_1 = \Gamma_{11}^2 \frac{\sqrt{EG-F^2}}{E\sqrt{E}}, (\Gamma_{11}^2 = \frac{-E_v}{2G}) = -\frac{E_v}{2E\sqrt{G}}$

在 v-curve 上, $du=0, \frac{dv}{ds} = \frac{1}{\sqrt{G}}, \kappa_2 = \dots = \frac{G_u}{2G\sqrt{E}}$

$$\begin{aligned} \int_C \kappa_1 \sqrt{E}du + \kappa_2 \sqrt{G}dv &= \iint_A \left[\frac{\partial}{\partial u} (\kappa_2 \sqrt{G}) - \frac{\partial}{\partial v} (\kappa_1 \sqrt{E}) \right] dudv \dots (\ast) \\ &= \iint_A \left[\frac{\partial}{\partial u} \left(\frac{G_u}{2\sqrt{EG}} \right) + \frac{\partial}{\partial v} \left(\frac{E_v}{2\sqrt{EG}} \right) \right] dudv \\ &= \iint_A -K \sqrt{EG} dudv = -\iint_A K dA \end{aligned}$$

$$\begin{aligned} (F=0 \text{ 時}, K &= -\frac{1}{\sqrt{EG}} \left\{ \frac{\partial}{\partial u} \left(\frac{1}{\sqrt{E}} \frac{\partial \sqrt{G}}{\partial u} \right) + \frac{\partial}{\partial v} \left(\frac{1}{\sqrt{G}} \frac{\partial \sqrt{E}}{\partial v} \right) \right\} \dots \text{尚待證明} \\ &= -\frac{1}{\sqrt{EG}} \left\{ \frac{\partial}{\partial u} \left(\frac{G_u}{2\sqrt{EG}} \right) + \frac{\partial}{\partial v} \left(\frac{E_v}{2\sqrt{EG}} \right) \right\} \end{aligned}$$

所以 當 C 是 M 上一 Jordan Curve

$$\begin{aligned} \int_C \kappa_g ds &= \int_C d\theta - \iint_A K dA \\ \iint_A K dA + \int_C \kappa_g ds &= \int_C d\theta = 2\pi \end{aligned}$$

取一平行向量場 $Z = \cos \alpha e_1 + \sin \alpha e_2$, $(\frac{dZ}{dt})^T = 0$, 證明 $\frac{d\alpha}{dt} = -g_u \frac{dv}{dt}$

$$\frac{dZ}{dt} = (-\sin \alpha e_1 + \cos \alpha e_2) \frac{d\alpha}{dt} + (\cos \alpha \frac{de_1}{dt} + \sin \alpha \frac{de_2}{dt})$$

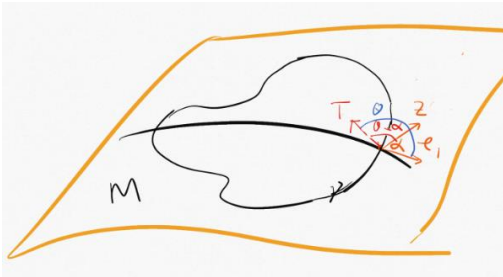
$$0 = \frac{dZ}{dt} \cdot e_2 = \cos \alpha \frac{d\alpha}{dt} + \cos \alpha \left(\frac{de_1}{dt} \cdot e_2 \right), \text{ 所以}$$

$$\begin{aligned} \frac{d\alpha}{dt} &= -\frac{de_1}{dt} \cdot e_2 = -\left(\frac{\partial X_u}{\partial u} \frac{du}{dt} + \frac{\partial X_u}{\partial v} \frac{dv}{dt} \right) \cdot \frac{X_v}{g} \\ &= -\langle X_{uu}, \frac{X_v}{g} \rangle \frac{du}{dt} - \langle X_{uv}, \frac{X_v}{g} \rangle \frac{dv}{dt} \\ &= 0 - X_{uv} \cdot X_v \frac{1}{g} \frac{dv}{dt} \quad (X_{uv} \cdot X_v = \frac{\partial}{\partial u} \left(\frac{1}{2} g^2 \right)) \end{aligned}$$

$$= -g_u \frac{dv}{dt}$$

Green 定理 $\int_{\gamma} Pdu + Qdv = \iint_A \left(\frac{\partial Q}{\partial u} - \frac{\partial P}{\partial v} \right) dudv$

$$\begin{aligned} \delta_{\gamma} \alpha &= \int_a^b \left(\frac{d\alpha}{dt} \right) dt = \int_a^b \left(-g_u \frac{dv}{dt} \right) dt = \int_{\gamma} -g_u dv = \iint_A -g_{uu} dudv \\ &= \iint_A \frac{-g_{uu}}{g} d\sigma = \iint_A K d\sigma \quad (\text{因為 } d\sigma = g dudv) \end{aligned}$$



$$T = \frac{d\lambda}{ds} = \cos \theta e_1 + \sin \theta e_2$$

由切線轉角定理 $\delta_{\gamma} \theta = 2\pi$

沿 γ 的平行向量場 $Z = \cos \alpha e_1 + \sin \alpha e_2$

$$\theta = \alpha + (\theta - \alpha)$$

$$2\pi = \delta_{\gamma} \theta = \delta_{\gamma} \alpha + \delta_{\gamma} (\theta - \alpha) = \iint_A K d\sigma + \int_{\gamma} \frac{d}{ds} (\theta - \alpha) ds$$

以下證明 $\frac{d}{ds} (\theta - \alpha) = \kappa_g$

$$T = \cos \theta e_1 + \sin \theta e_2, N = -\sin \theta e_1 + \cos \theta e_2$$

$$\frac{dT}{ds} = (-\sin \theta e_1 + \cos \theta e_2) \frac{d\theta}{ds} + \cos \theta \frac{de_1}{ds} + \sin \theta \frac{de_2}{ds}$$

$$\kappa_g = \left(\frac{dT}{ds} \right)^T = \frac{dT}{ds} \cdot N$$

$$= (\sin^2 \theta + \cos^2 \theta) \frac{d\theta}{ds} + (-\sin^2 \theta \frac{de_2}{ds} \cdot e_1 + \cos^2 \theta \frac{de_1}{ds} \cdot e_2)$$

$$= \frac{d\theta}{ds} + \frac{de_1}{ds} \cdot e_2 = \frac{d\theta}{ds} - \frac{d\alpha}{ds} = \frac{d}{ds} (\theta - \alpha)$$

$$\text{得 } \iint_A K d\sigma + \int_{\gamma} \kappa_g ds = 2\pi$$

曲面 $M: X = X[u, v]$ ，以下建立么速測地坐標系，

$$X_u = \frac{\partial X}{\partial u}, X_v = \frac{\partial X}{\partial v}, \text{ 使得 } E=1, F=0, ds^2 = du^2 + Gdv^2$$

$$\text{取 } e_1 = X_u, e_2 = X_v / g, e_3 = \frac{X_u \times X_v}{g} = N, g^2 = G = X_v \cdot X_v$$

$$(|e_2| = \left| \frac{X_v \cdot X_v}{g^2} \right| = \frac{G}{g^2} = 1)$$

$$K = \kappa_1 \kappa_2 = \frac{N_u \times N_v}{X_u \times X_v} = \frac{\det(b_{ij})}{\det(g_{ij})} = \frac{eg - f^2}{EG - F^2}$$

$$N_u = \langle N_u, e_1 \rangle e_1 + \langle N_u, e_2 \rangle e_2$$

$$N_v = \langle N_v, e_1 \rangle e_1 + \langle N_v, e_2 \rangle e_2$$

$$\begin{aligned} N_u \times N_v &= \{ \langle N_u, e_1 \rangle \langle N_v, e_2 \rangle - \langle N_u, e_2 \rangle \langle N_v, e_1 \rangle \} e_1 \times e_2 \\ &= \frac{1}{g^2} \{ \langle N_u, X_u \rangle \langle N_v, X_v \rangle - \langle N_u, X_v \rangle \langle N_v, X_u \rangle \} X_u \times X_v \\ &= \frac{1}{g^2} \{ \langle N, X_{uu} \rangle \langle N, X_{vv} \rangle - \langle N, X_{uv} \rangle^2 \} X_u \times X_v \end{aligned}$$

(由 $N \cdot X_u = 0$, 得 $N_u \cdot X_u = -N \cdot X_{uu}$ 。 由 $N \cdot X_v = 0$, 得 $N_v \cdot X_v = -N \cdot X_{vv}$)

同理 $N_u \cdot X_v = N_v \cdot X_u = -N \cdot X_{uv}$)

由 $\frac{\partial}{\partial u} X_{uv} - \frac{\partial}{\partial v} X_{uu} = 0$, 兩邊對 X_v 作內積

$$\langle \frac{\partial}{\partial u} X_{uv}, X_v \rangle - \langle \frac{\partial}{\partial v} X_{uu}, X_v \rangle = 0$$

$$\left(\frac{\partial}{\partial u} \langle X_{uv}, X_v \rangle = \langle \frac{\partial}{\partial u} X_{uv}, X_v \rangle + \langle X_{uv}, X_{uv} \rangle \right)$$

$$\frac{\partial}{\partial u} \langle X_{uv}, X_v \rangle - \langle X_{uv}, X_{uv} \rangle - \frac{\partial}{\partial v} (X_{uu}, X_v) + \langle X_{uu}, X_{vv} \rangle = 0 \dots\dots (\ast)$$

$$g^2 = X_v \cdot X_v$$

$$\frac{\partial}{\partial u} g^2 = X_{uv} \cdot X_v + X_v \cdot X_{uv} , \text{ 所以 } X_{uv} \cdot X_v = \frac{1}{2} \frac{\partial}{\partial u} g^2 = gg_u$$

$$\frac{\partial}{\partial u} \langle X_{uv}, X_v \rangle = \frac{\partial}{\partial u} gg_u = g_u^2 + gg_{uu} \dots (1)$$

$$X_{uv} = \langle X_{uv}, X_u \rangle X_u + \langle X_{uv}, X_v \rangle \frac{X_v}{g^2} + \langle X_{uv}, N \rangle N$$

$$-\langle X_{uv}, X_{uv} \rangle = -\frac{1}{g^2} \langle X_{uv}, X_v \rangle^2 - \langle X_{uv}, N \rangle^2 \dots (2)$$

$$\left(\text{因為 } g^2 = X_u \cdot X_u, \frac{\partial}{\partial u} g^2 = X_{uu} \cdot X_u + X_u \cdot X_{uu} = 2X_{uu} \cdot X_u\right)$$

$$= -\frac{1}{g^2} \left(\frac{\partial}{\partial u} \left(\frac{1}{2} g^2\right)\right)^2 - \langle X_{uu}, N \rangle^2 = -g_u^2 - \langle X_{uu}, N \rangle^2$$

$$\frac{\partial}{\partial v} \langle X_{uu}, X_v \rangle = 0 \dots (3)$$

$$\left(\text{因為 } X_{uu} = \frac{1}{g} X_u + \frac{1}{g} X_u + \frac{1}{g} N = \frac{2}{g} X_u + \frac{1}{g} N, \langle X_v, N \rangle = 0\right)$$

$$X_{uu} \text{ 只有法部, 所以 } X_{uu} = \langle X_{uu}, N \rangle N$$

$$\langle X_{uu}, X_{vv} \rangle = \langle \langle X_{uu}, N \rangle N, X_{vv} \rangle = \langle X_{uu}, N \rangle \langle X_{vv}, N \rangle \dots (4)$$

(*) 變成

$$g g_{uu} - \langle X_{uv}, N \rangle^2 + \langle X_{uu}, N \rangle \langle X_{vv}, N \rangle = 0$$

$$\text{其中 } -\langle X_{uv}, N \rangle^2 + \langle X_{uu}, N \rangle \langle X_{vv}, N \rangle = g^2 K$$

$$\text{所以 } K = \frac{-g_{uu}}{g}$$

§ 04 應用

1. [Hairy ball theorem](#) : There does not exist a non-vanishing continuous tangent vector field X on a sphere S^2
2. The Poincare-Hopf index theorem
Let X be a differentiable tangent vector field on a compact surface S which has only finitely many isolated singular points p_1, \dots, p_n . Then $\sum_i \mu(p_i) = \chi(S)$
 $\mu(p)$ is the index of singular point p .
3. [Jacobi 定理](#)
4. 一個正曲率的緊緻(compact)曲面與球面同胚
5. T 是一個測地線三角形, 則其三內角和 = (1) $= \pi$ if $K=0$ (2) $> \pi$ if $K>0$ (3) $< \pi$ if $K<0$

§05 討論

1. 對一個平面上的曲線, $K=0$, 回到切線轉角定理。
2. 半徑= a 的球面, 平面 E 到球心的距離= d , 和球面截出一圓 C , P 是 C 上一點,

$$\text{求 } \kappa_g(P) = \dots \frac{d}{ar}, (r = \sqrt{a^2 - d^2}) \text{ 是小圓半徑}$$

$$X(\theta, \varphi) = [a \cos \theta \cos \varphi, a \cos \theta \sin \varphi, a \sin \theta]$$

$$X_\theta = [-a \sin \theta \cos \varphi, -a \sin \theta \sin \varphi, a \cos \theta]$$

$$X_\varphi = [-a \cos \theta \sin \varphi, a \cos \theta \cos \varphi, 0]$$

$$E = a^2, F = 0, G = a^2 \cos^2 \theta$$

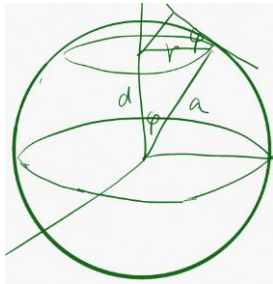
$$dA = \sqrt{EG - F^2} d\theta d\varphi = a^2 \cos \theta d\theta d\varphi$$

$$\iint_A K dA = \int_0^{2\pi} \int_{\theta_0}^{\pi/2} \cos \theta d\theta d\varphi, \text{ 其中 } \sin \theta_0 = \frac{d}{a}$$

$$= 2\pi \left(1 - \frac{d}{a}\right)$$

$$\int_C \kappa_g ds = 2\pi r \kappa_g = 2\pi - 2\pi \left(1 - \frac{d}{a}\right) = 2\pi \frac{d}{a}, \text{ 所以 } \kappa_g = \frac{d}{ar}$$

another viewpoint



小圓的曲率 = $\frac{1}{r}$ 在切平面的投影

$$\kappa_g = \frac{1}{r} \cos \varphi = \frac{1}{r} \times \frac{d}{a} = \frac{d}{ar}$$

Consider a polar cap S on a round sphere of radius 1 ,

Then Area $S =$

$$\text{Area } S = \int_0^\theta 2\pi \sin \theta d\theta = 2\pi (1 - \cos \theta),$$

$$\text{hence } \int_S K d(\text{area}) = 1 \times \text{Area } S = 2\pi (1 - \cos \theta).$$

The curvature κ of $\partial S = 1/\text{radius} = 1/\sin \theta$.

The geodesic curvature κ_g of ∂S is $\cos \theta / \sin \theta$, hence

$$\begin{aligned} \int_{\partial S} \kappa_g ds &= \kappa_g \times \text{length}(\partial S) \\ &= (\cos \theta / \sin \theta) 2\pi \sin \theta = 2\pi \cos \theta. \end{aligned}$$

Therefore

$$\begin{aligned} \int_S K d(\text{area}) + \int_{\partial S} \kappa_g ds &= 2\pi (1 - \cos \theta) + 2\pi \cos \theta \\ &= 2\pi = 2\pi \chi(S). \end{aligned}$$

§ 06 Euler 特徵數



另一個重要的不變量是尤拉特徵數：多面體的 $V-E+F=2$

在[笛卡爾的秘密手記]一書中，據稱他發現了尤拉特徵數，基於某種原因他並沒有發表。

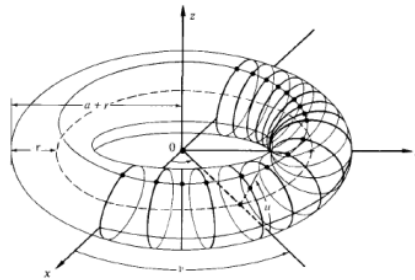
笛卡爾有記錄清醒夢(lucid dream)的習慣，1637年他因為清醒夢創立了坐標系。

這裡有一個研究清醒夢的平台。

透過感官引發清明夢的功夫稱太玄功，姑且聽之。

§ Gaussian Curvature of a Torus

Example 4.2. A torus T is created by rotating a radius r circle around a straight line distance a ($a > r$) away. Consider a particular parametrization (Figure 5): $\mathbf{x}(u, v) = ([a + r\cos(u)]\cos(v), [a + r\cos(u)]\sin(v), r\sin(u))$ where $u, v \in (0, 2\pi)$



$$\begin{aligned}\mathbf{x}_u &= (-r\sin(u)\cos(v), -r\sin(u)\sin(v), r\cos(u)) \\ \mathbf{x}_v &= (-[a + r\cos(u)]\sin(v), [a + r\cos(u)]\cos(v), 0) \\ \mathbf{x}_{uu} &= (-r\cos(u)\cos(v), -r\cos(u)\sin(v), -r\sin(u)) \\ \mathbf{x}_{uv} &= (r\sin(u)\sin(v), -r\sin(u)\cos(v), 0) \\ \mathbf{x}_{vv} &= (-[a + r\cos(u)]\cos(v), -[a + r\cos(u)]\sin(v), 0)\end{aligned}$$

As a result, $E = \langle \mathbf{x}_u, \mathbf{x}_u \rangle = r^2$, $F = \langle \mathbf{x}_u, \mathbf{x}_v \rangle = 0$, $G = \langle \mathbf{x}_v, \mathbf{x}_v \rangle = [a + r\cos(u)]^2$.

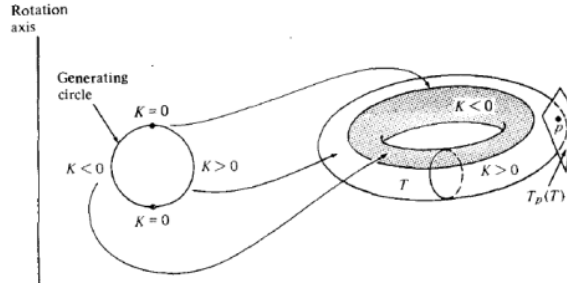
$$\begin{aligned}e &= -\langle N_u, \mathbf{x}_u \rangle = \langle N, \mathbf{x}_{uu} \rangle \\ &= \left\langle \frac{\mathbf{x}_v \wedge \mathbf{x}_u}{|\mathbf{x}_v \wedge \mathbf{x}_u|}, \mathbf{x}_{uu} \right\rangle \\ &= \frac{\det(\mathbf{x}_u, \mathbf{x}_v, \mathbf{x}_{uu})}{\sqrt{EG - F^2}} \\ &= \frac{r^2[a + r\cos(u)]}{r[a + r\cos(u)]} \\ &= r\end{aligned}$$

Similarly, $f = 0, g = \cos(u)[a + r\cos(u)]$. Therefore,

$$K = \frac{eg - f^2}{EG - F^2} = \frac{\cos(u)}{r[a + r\cos(u)]}.$$

As Figure 6 below illustrates, the torus T can be divided into 3 parts by the signs of the Gaussian curvature:

1. $K > 0$ when $u \in (0, \frac{\pi}{2})$ or $u \in (\frac{3}{2}\pi, 2\pi)$
2. $K = 0$ when $u = \frac{\pi}{2}$ or $u = \frac{3}{2}\pi$
3. $K < 0$ when $u \in (\frac{\pi}{2}, \frac{3}{2}\pi)$



Theorem 6.7 (The Global Gauss-Bonnet Theorem).

Let $R \subset S$ be a regular region of an oriented surface and let C_1, \dots, C_n be the closed, simple, piecewise regular curves which form the boundary ∂R of R . Suppose that each C_i is positively oriented and let $\theta_1, \dots, \theta_p$ be the set of all external angles of the curves C_1, \dots, C_n . Then

$$\sum_{i=1}^n \int_{C_i} k_g(s) ds + \iint_R K d\sigma + \sum_{i=1}^p \theta_i = 2\pi\chi(R)$$

where s is the arc length of C_i , and the integral over C_i means the sum of integrals in every regular arc of C_i .

1. 怎麼說它有多彎？ 曹亮吉
2. 高斯曲率到黎曼流形上稱為截曲率。
3. 維數大於 2 的黎曼流形黎曼引入一個抽象且嚴格的方法，就是黎曼曲率張量。

$$R(u, v)w = \nabla_u \nabla_v w - \nabla_v \nabla_u w - \nabla_{[u, v]} w$$