$$z = \sinh x \sqrt{1 - (\frac{y}{\cosh x})^2}$$
 \neq mean curvature H=

$$\sinh x = \frac{e^x - e^{-x}}{2}$$
, $\cosh x = \frac{e^x + e^{-x}}{2}$, $\cosh^2 x - \sinh^2 x = 1$

$$H = \frac{eG - 2fF + gE}{2(EG - F^2)}$$

 $X(x,\theta) = (x,\cosh x \sin \theta, \sinh x \cos \theta)$

 $X_x = (1, \sinh x \sin \theta, \cosh x \cos \theta)$

 $X_{\theta} = (0, \cosh x \cos \theta, -\sinh x \sin \theta)$

$$E = X_x \cdot X_x = 1 + \sinh^2 x \sin^2 \theta + \cosh^2 x \cos^2 \theta$$

$$F = X_{r} \cdot X_{\theta} = 0$$

$$G = X_{\theta} \cdot X_{\theta} = \cosh^2 x \cos^2 \theta + \sinh^2 x \sin^2 \theta$$

$$X_x \times X_\theta = (-\sinh^2 x - \cos^2 \theta, \sinh x \sin \theta, \cosh x \cos \theta)$$

$$\left|X_{x} \times X_{\theta}\right|^{2} =$$

$$N = \frac{X_x \times X_\theta}{\left| X_x \times X_\theta \right|} = \frac{\dots}{\sqrt{(\sinh^2 x + \cos^2 \theta)(\sin^2 x + \cos^2 \theta + 1)}}$$

$$X_{xx} = (0, \cosh x \sin \theta, \sinh x \cos \theta)$$

$$X_{x\theta} = (0, \sinh x \cos \theta, -\cosh x \sin \theta)$$

$$X_{\theta\theta} = (0, -\cosh x \sin \theta, -\sinh x \cos \theta)$$

$$e = \frac{\cosh x \sinh x}{\sqrt{(\sinh^2 x + \cos^2 \theta)(\sinh^2 x + \cos^2 \theta + 1)}}$$

$$g = \frac{-\cosh x \sinh x}{\sqrt{(\sinh^2 x + \cos^2 \theta)(\sinh^2 x + \cos^2 \theta + 1)}}$$

$$H = \frac{eG + gE}{2EG} = \frac{e(G-E)}{2EG} = \frac{-e}{2EG}$$

For fixed x ,
$$(\frac{y}{\cosh x})^2 + (\frac{z}{\sinh x})^2 = \cos^2 \theta + \sin^2 \theta = 1$$

This symmetry implies the surface is rotationally invariant around the x-axis,a hallmark(標誌) of minimal surfaces like the catenoid。

The term e contains coshxsinhx in the numerator , but for a minimal surface , these terms must inherently(本質上) cancel globally due to the surface's geometric constraints

(e.g., the identity $\cosh^2 x - \sinh^2 x = 1$) Catenoid:

$$\begin{cases} x = c \cosh(\frac{v}{c}) \cos u \\ y = c \sinh(\frac{v}{c}) \sin u \\ z = v \end{cases}$$

For fixed x ,
$$(\frac{y}{\cosh x})^2 + (\frac{z}{\sinh x})^2 = \cos^2 \theta + \sin^2 \theta = 1$$
 is a catenoid \circ

The term e contains $\cosh x \sinh x$ in the numerator, but H must vanish (H=0) for a minimal surface. This forces the **geometric cancellation** of $\cosh x \sinh x$ through two mechanisms:

- 1. Hyperbolic Identity: The identity $\cosh^2 x \sinh^2 x = 1$ is implicitly embedded in the parameterization, ensuring that contributions from $\cosh x \sinh x$ are counterbalanced by the surface's curvature structure.
- 2. Symmetry of the Parameterization: The rotational symmetry ensures that the positive and negative contributions of $\cosh x \sinh x$ (via e and g=-e) cancel globally when integrated over the surface. This is a hallmark of minimal surfaces, where stretching and compression effects balance perfectly.

The geometric constraints of minimality (H=0) and the symmetry of the catenoid parameterization force the coshxsinhx terms to cancel identically \circ This cancellation is not algebraic but **geometric**, arising from the *surface's* intrinsic balance of curvature contributions \circ

Thus, H=0