

§ Cartan Computations

Let E_1, \dots, E_n be an orthonormal frame field, $\omega^1, \dots, \omega^n$, its dual forms is the

orthonormal coframe field with $\omega^i(E_j) = \delta_j^i$

Definition :

The connection forms of a frame field E_1, \dots, E_n are the one-forms ω_j^i such that

for all tangent vectors v , $\omega_j^i(v) = \omega^i(\nabla_v E_j)$ for all i, j

Hence by the duality formula, $\nabla_v E_j = \sum \omega_j^m(v) E_m$

$\omega_j^k := \sum_i \Gamma_{ij}^k \omega^i$, $R_{vw}(E_j) = \sum_i \Omega_j^i(v, w) E_i$, for tangent vectors v, w

Where Ω_j^i is a two-form called the curvature forms of the frame field.

1. $d\omega^i = \sum_j \omega^j \wedge \omega_j^i$
2. $\Omega_j^i = d\omega_j^i - \sum_k \omega_j^k \wedge \omega_k^i$
3. $R_{jkl}^i = \Omega_j^i(E_k, E_l)$ curvature tensor

The sectional curvatures of the frame field 2-planes are $K(\Pi_{ij}) = K(E_i, E_j) = \varepsilon_j R_{jij}^i$

Where $\varepsilon_i = \langle E_i, E_i \rangle$

$\Omega_j^i = -\varepsilon_i \varepsilon_j \Omega_i^j$. In particular, $\Omega_i^i = 0$

Remarks :

Let $\{E_i\}$ be an orthonormal frame field on M

1. If M is a Riemannian manifold, the signs ε_i are all $+1$, (ω_j^i) and (Ω_j^i) are skew-symmetric.
2. If M is a Lorentz manifold, then $\omega_i^0 = \omega_0^i$, but $\omega_j^i = -\omega_i^j$ for $i, j > 0$, and similarly for Ω_j^i

Let u, v be orthogonal coordinates in a semi-Riemannian surface S ◦

$$\langle \partial_u, \partial_u \rangle = E = \varepsilon_1 e^2, \langle \partial_v, \partial_v \rangle = G = \varepsilon_2 g^2, \text{ where } \varepsilon_1, \varepsilon_2 \text{ are } \pm 1, e > 0, g > 0. \circ$$

$$\text{Then the Gaussian curvature of } S, K_S = \frac{-1}{eg} \left[\varepsilon_1 \left(\frac{e_v}{g} \right)_v + \varepsilon_2 \left(\frac{g_u}{e} \right)_u \right]$$

Prove

$$\text{Define } E_1 = \frac{\partial_u}{e}, E_2 = \frac{\partial_v}{g}, \text{ an orthonormal fram field}$$

$$\text{Then the Gaussian curvature } K_S = \langle \Omega_2^1(E_1, E_2)E_1, E_1 \rangle = \varepsilon_1 \Omega_2^1(E_1, E_2)$$

$$\text{The dual coframe is } \omega^1 = edu, \omega^2 = gdv$$

$$d\omega^1 = e_v dv \wedge du = -\frac{e_v}{g} du \wedge \omega^2 = \omega^2 \wedge \omega_2^1$$

$$d\omega^2 = g_u du \wedge dv = -\frac{g_u}{e} dv \wedge \omega^1 = \omega^1 \wedge \omega_1^2$$

$$\omega_2^1 = \frac{e_v}{g} du - \varepsilon_1 \varepsilon_2 \frac{g_u}{e} dv \quad (\omega_2^1 = -\varepsilon_1 \varepsilon_2 \omega_1^2)$$

$$\Omega_1^2 = d\omega_1^2$$

$$\begin{aligned} d\omega_2^1 &= \left(\frac{e_v}{g} \right)_v dv \wedge du - \varepsilon_1 \varepsilon_2 \left(\frac{g_u}{e} \right)_u du \wedge dv \\ &= -\left[\left(\frac{e_v}{g} \right)_v + \varepsilon_1 \varepsilon_2 \left(\frac{g_u}{e} \right)_u \right] du \wedge dv \end{aligned}$$

$$\begin{aligned} K_S &= \varepsilon_1 \Omega_2^1(E_1, E_2) = \varepsilon_1 d\omega_2^1(E_1, E_2) = \varepsilon_1 d\omega_2^1 \left(\frac{\partial_u}{e}, \frac{\partial_v}{g} \right) \\ &= -\varepsilon_1 \left[\left(\frac{e_v}{g} \right)_v + \varepsilon_1 \varepsilon_2 \left(\frac{g_u}{e} \right)_u \right] / (eg) \end{aligned}$$

$$\text{In classical differential geometry } K = \frac{eg - f^2}{EG - F^2}$$

$$\text{Where } E = X_u \cdot X_u, G = X_v \cdot X_v, F = X_u \cdot X_v$$

$$e = X_{uu} \cdot N, g = X_{vv} \cdot N, f = X_{uv} \cdot N$$

$$\text{在測地坐標系中, } ds^2 = du^2 + g^2 dv^2, X_u \cdot X_u = 1, X_v \cdot X_v = g^2$$

$$\text{從 } \frac{\partial}{\partial u} X_{uv} = \frac{\partial}{\partial v} X_{uu} \text{ 出發, 兩邊對 } X_v \text{ 做內積, 可以推出 } K = -\frac{g_{uv}}{g}$$

$$E_1 = \frac{\partial}{\partial u}, E_2 = \frac{1}{g} \frac{\partial}{\partial v}, \omega^1 = du, \omega^2 = g dv$$

$$d\omega^1 = 0$$

$$d\omega^2 = g_u du \wedge dv = \omega^1 \wedge \omega_1^2, \omega_1^2 = g_u dv$$

$$\Omega_1^2 = d\omega_1^2 = g_{uu} du \wedge dv$$

$$K = \Omega_2^1(E_1, E_2) = -\Omega_1^2(E_1, E_2) = -\frac{g_{uu}}{g}$$