## § Burger equation

TheBurger's equation is a fundamental partial differential equation (PDE) in fluid dynamics and **nonlinear wave theory**  $\circ$  It is a simplified model that combines nonlinearity and diffusion , and it is often used to study phenomena such as shock waves , turbulence , and traffic flow  $\circ$ 

The Burger's equation is given by :  $\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = v \frac{\partial^2 u}{\partial x^2}$ 

Where :

- 1. u(x,t) is the velocity field or the quantity of interest
- 2. t is time
- 3. xis the spatial coordinate
- 4. u is the kinematic viscosity (a constant representing diffusion)  $\circ$

Key Features:

1. Nonlinear Term  $u \frac{\partial u}{\partial x}$ : This term represents the nonlinear convection or advection, which causes wave steepening and can lead to the formation of shocks.

$$v \frac{\partial^2 u}{\partial^2 u}$$

2. Diffusion Term  $\partial x^2$ : This term represents viscous(黏稠的) diffusion, which

smooths out sharp gradients and prevents the formation of infinite discontinuities  $\,^\circ$ 

The Burger's equation is a prototypical(原型的) example of a PDE that balances nonlinearity and diffusion, making it a key equation in the study of nonlinear dynamics and applied mathematics。

Suppose u is a classical solution to the following initial-boundary value problem for a viscous Burger equation

 $\begin{cases} u_t + uu_x = u_{xx}, (x,t) \in (0,1) \times (0,\infty) \\ u(0,t) = u(1,t) = 0, t > 0 \\ u(x,0) = g(x), x \in [0,1] \end{cases}$ 

Here g(x) is a smooth function such that g(0)=g(1)=0

Show that

(a) 
$$\int_0^1 u^2(x,t) dx$$
 is decreasing (b)  $\int_0^1 u^2(x,t) dx$  tends to 0 exponentially  $\circ$